

# ESR12. Measuring dementia behaviours through depth sensors

Joint visuAAL-GoodBrother conference

**Alicante, Spain**

**18.06.2024**

**Irene Ballester Campos**

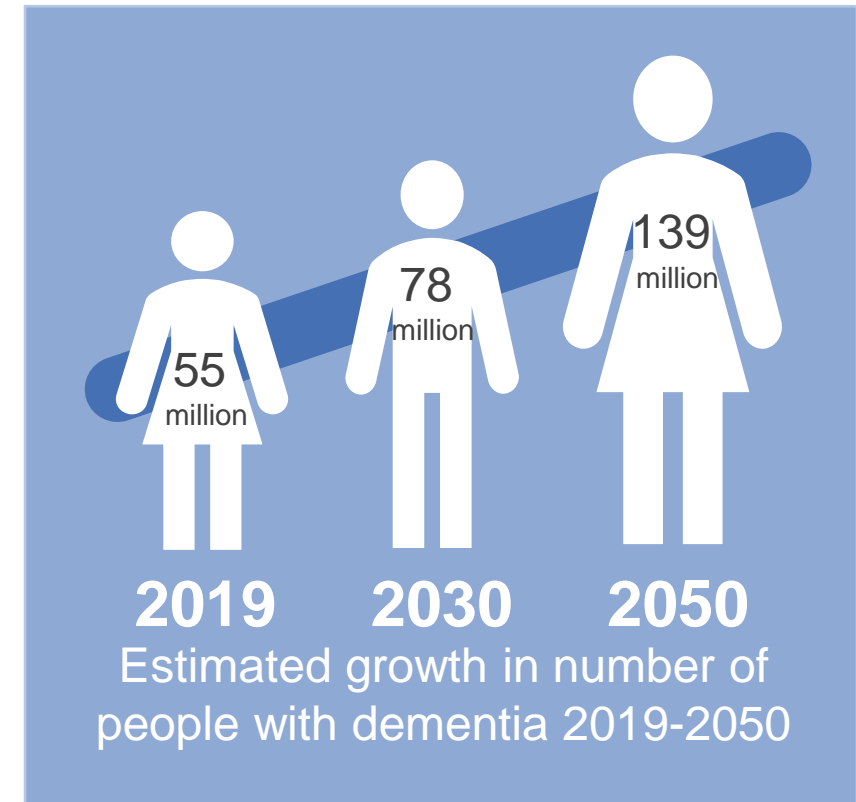
**Computer Vision Lab, TU Wien**

## What's dementia?

- Syndrome in which there is a **deterioration in cognitive functioning beyond what might be expected from normal ageing** [1]
- One of the **major causes of dependency** among older people [2]

## Why dementia?

- Behavioural changes **strongly correlated** with the degree of functional and cognitive impairment [2].
- **Behavioral and Psychological Symptoms of Dementia (BPSD)**: agitation, aberrant motor behaviour, anxiety, irritability, depression, apathy, delusions, changes in sleep or appetite [3].



Data source: WHO [1]

[1] World Health Organization <https://www.who.int/news-room/fact-sheets/detail/dementia> (accessed April 28, 2024)

[2] **Global status report on the public health response to dementia**. World Health Organization (2021)

[3] Joaquim Cerejeira, Luisa Lagarto, and Elizabeta Blagoja Mukaetova-Ladinska. "Behavioral and psychological symptoms of dementia". In: *Frontiers in neurology* 3 (2012), p. 73.

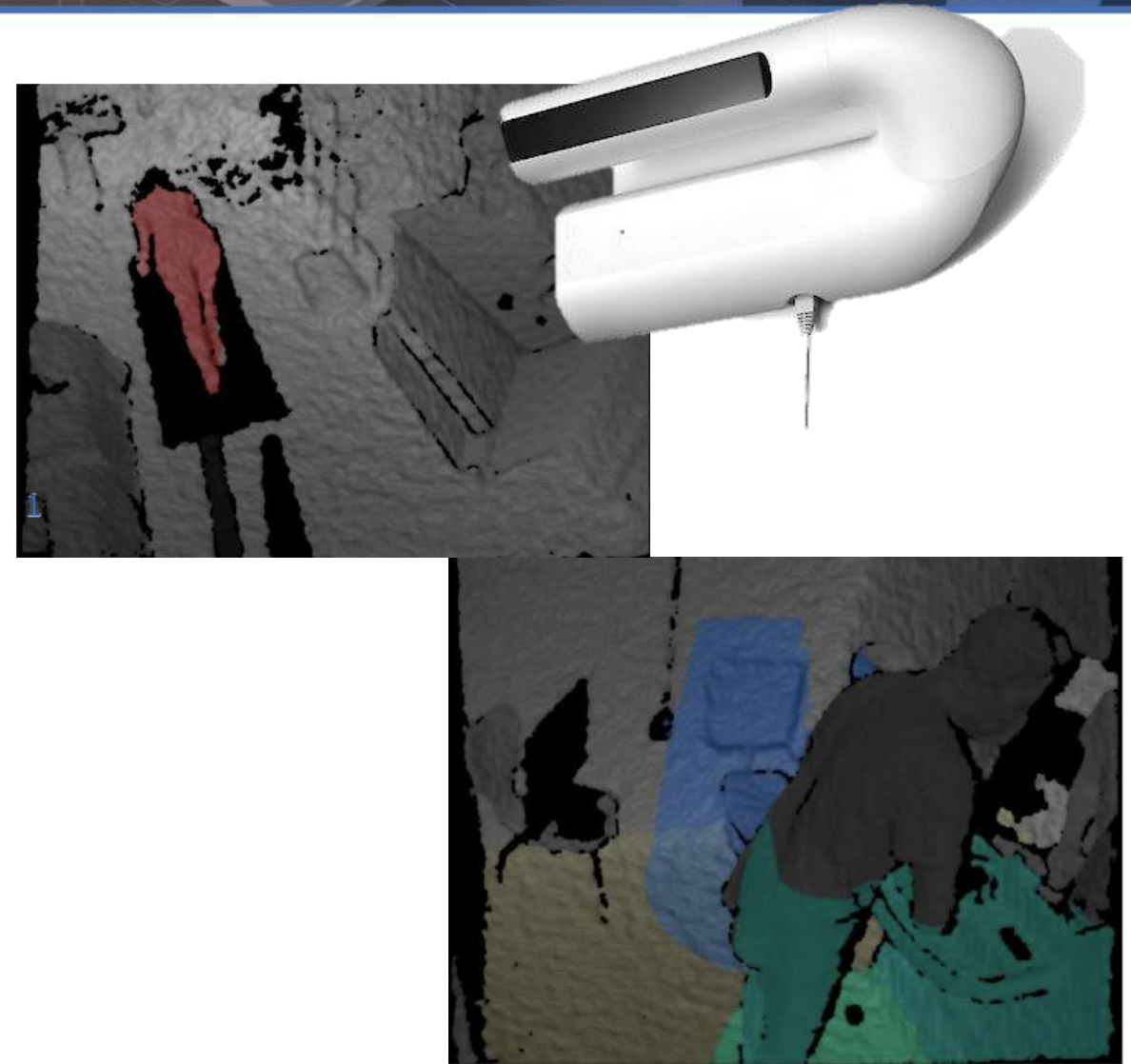
# Data modality: depth

One of the main concerns: **PRIVACY**

RGB



Depth



## AI for behaviour analysis from unobtrusive sensor data

Goal: Development of AI methods for **measuring** the **behaviours** of care home residents with **dementia** using **unobtrusive sensors (depth maps)**

In order to:

1. **Unobtrusive Remote Patient Monitoring**
2. **Provide assistance with ADLs**

## AI for behaviour analysis from unobtrusive sensor data

Goal: Development of AI methods for **measuring** the **behaviours** of care home residents with **dementia** using **unobtrusive sensors (depth maps)**

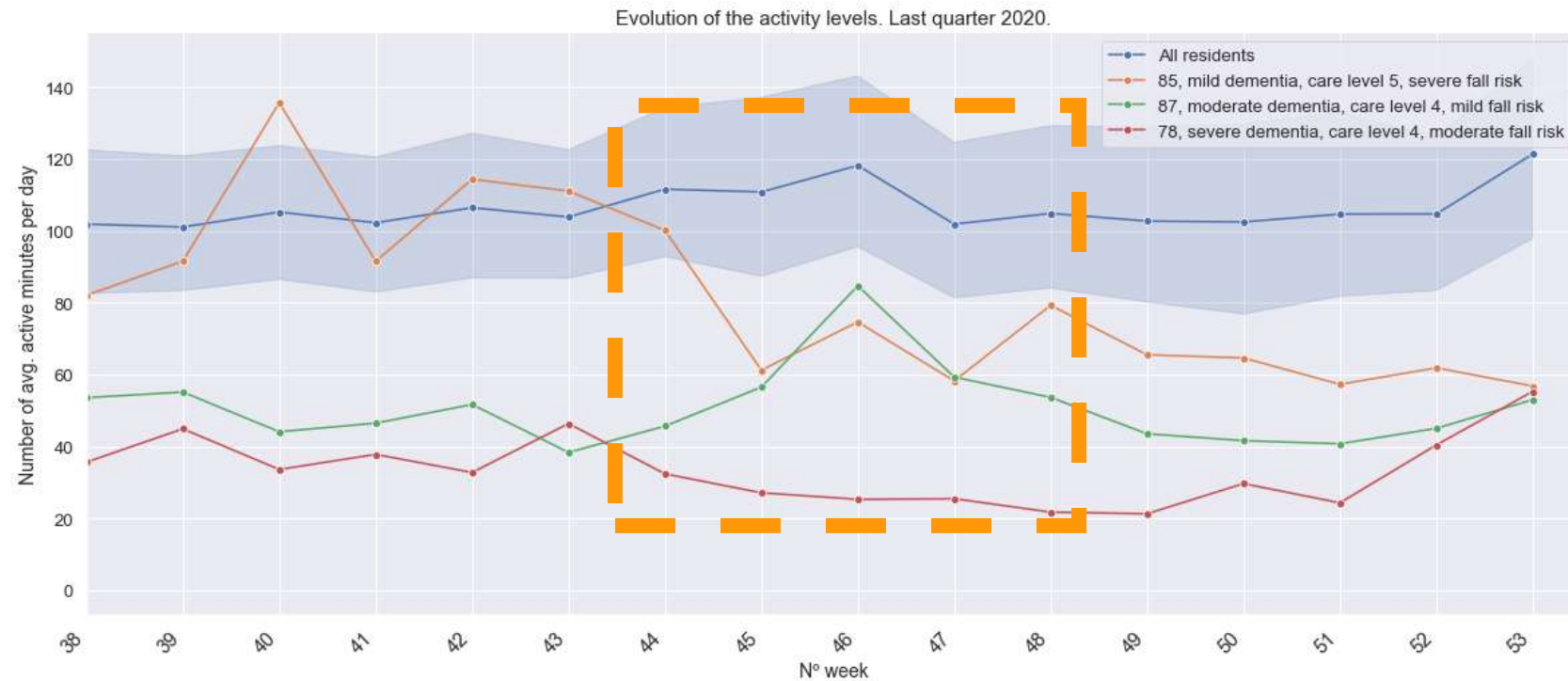
In order to:

1. **Unobtrusive Remote Patient Monitoring**
2. **Provide assistance with ADLs**



## Ultimate goal

Detect and measure functional and behavioural changes indicative of dementia



RQ1. Different inputs for behaviour measurement

RQ2. Robust performance for real-world HAR

RQ1. Different inputs for behaviour measurement

RQ2. Robust performance for real-world HAR

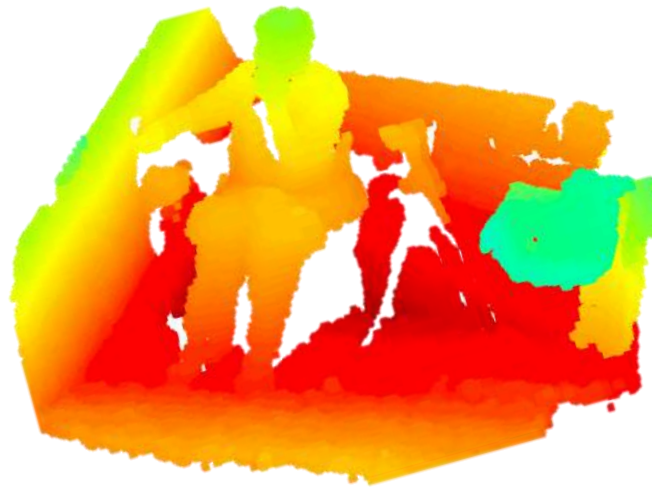


## Different inputs

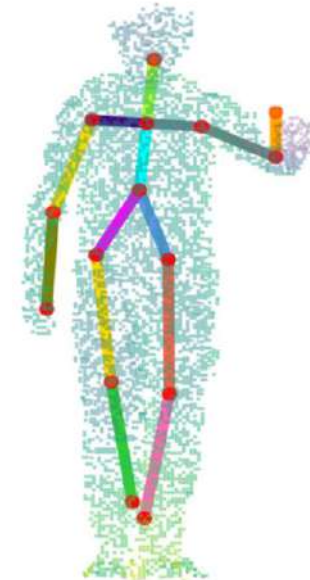
(Raw) depth images



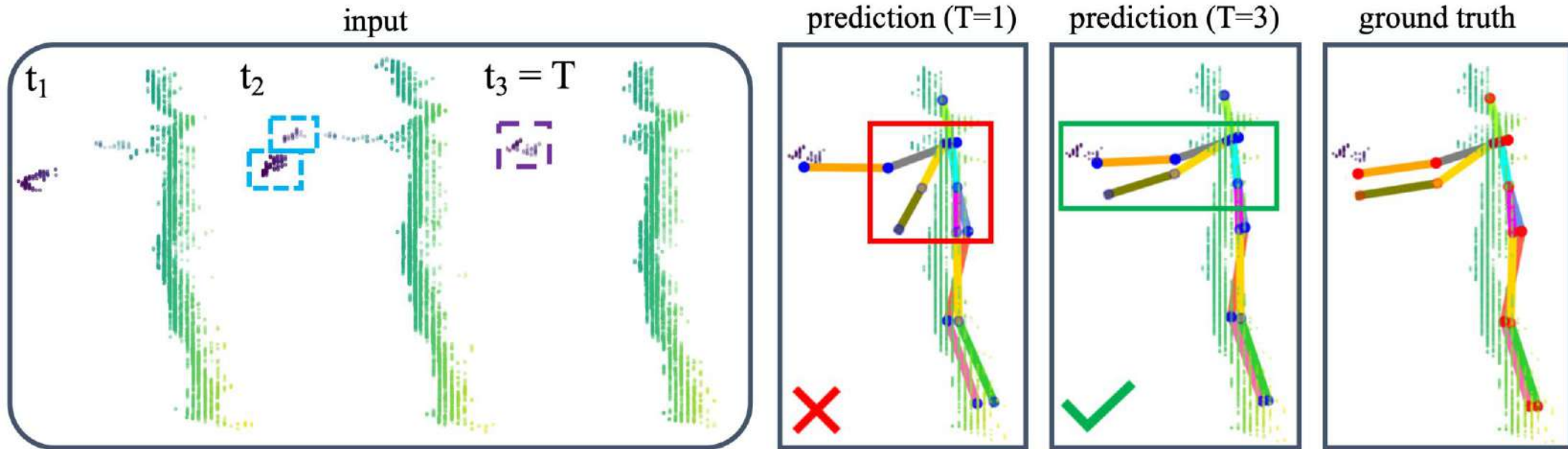
Point clouds from depth



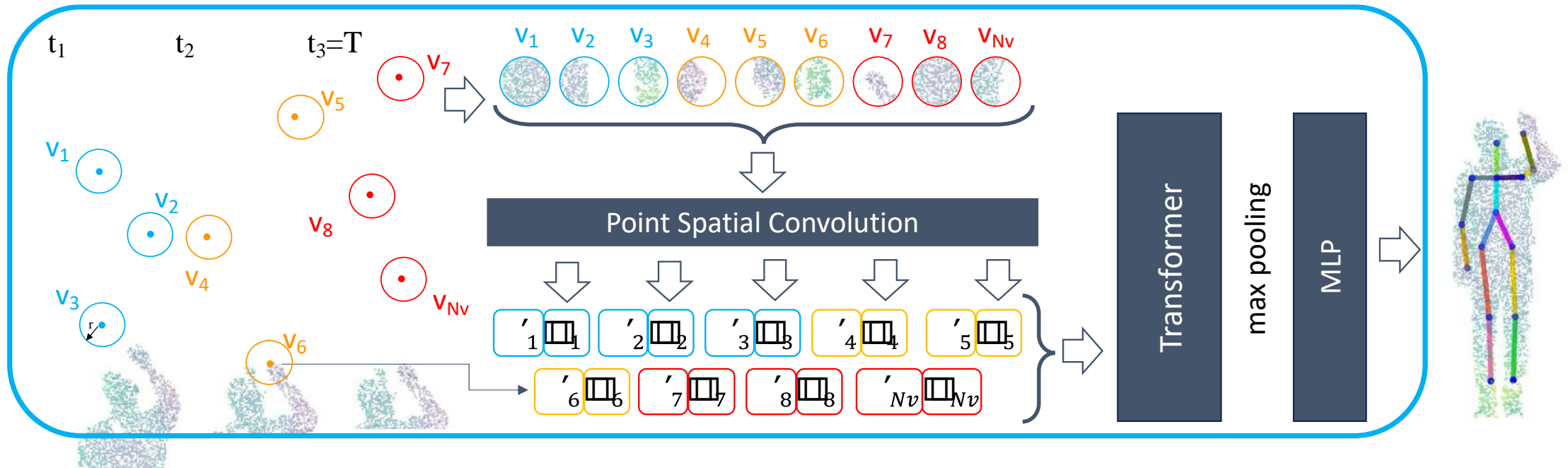
Skeletons from depth/point clouds



Motivation: Sequence information helps with occlusions and noise



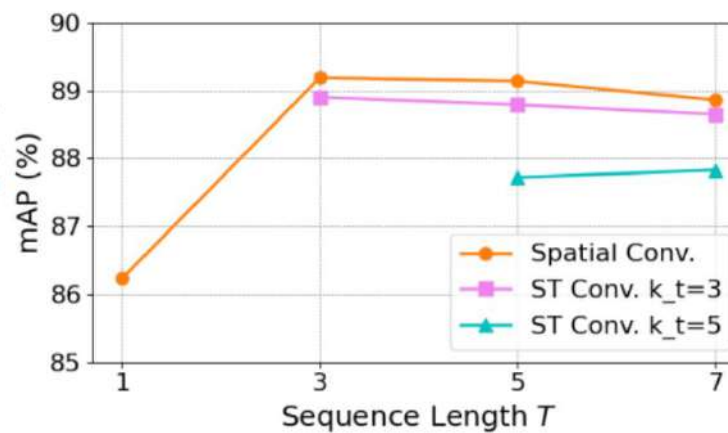
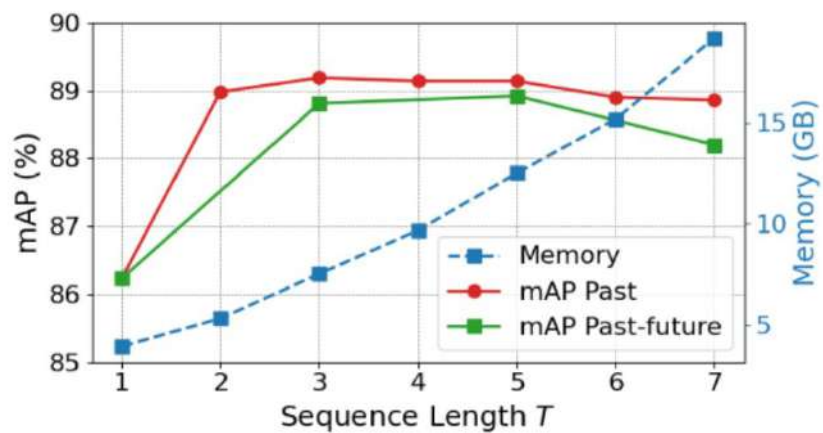
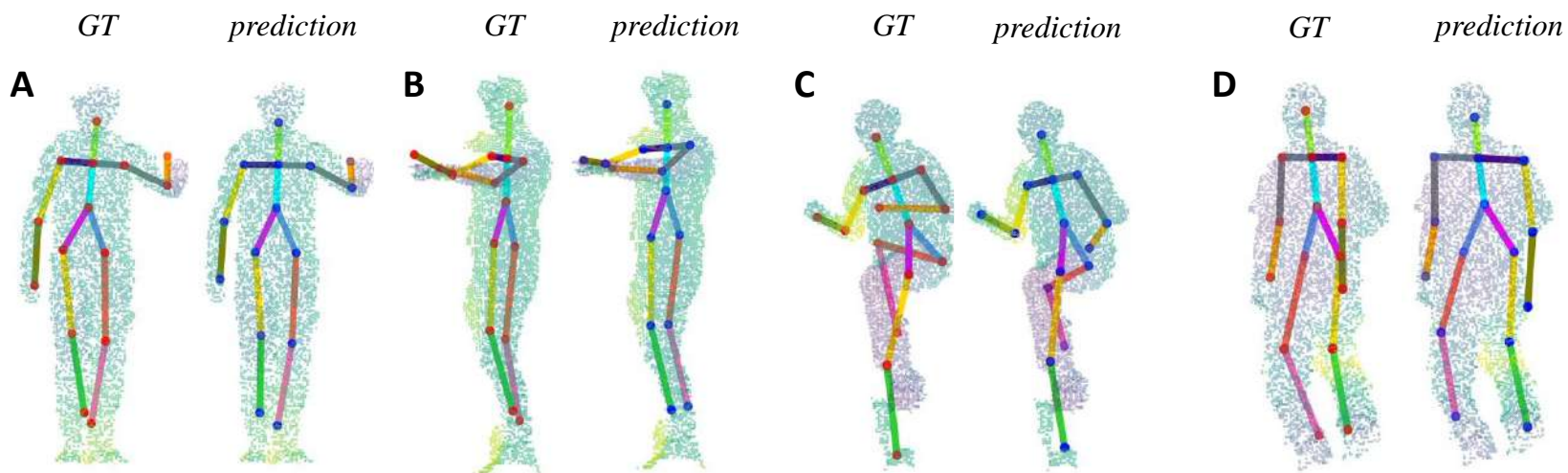
- How to process sequences of point clouds?
  - Spatial point convolution in local areas
  - Transformer + MLP for prediction of 3D joints



**Table 1.** Comparison with the state-of-the-art for ITOP front-view (0.1m mAP)

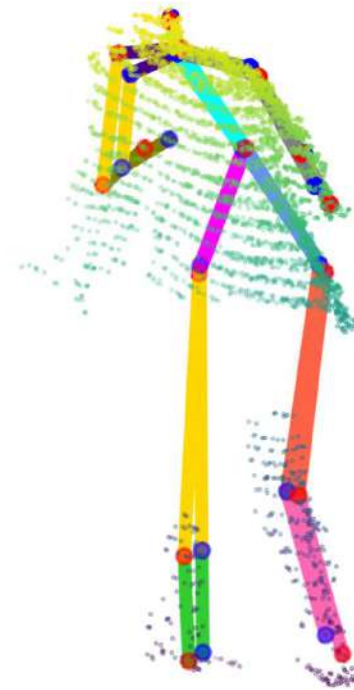
Method	Single Modality Methods						Multimodal Methods		
	V2V	A2J	WSM*	Zhou et al.	DECA	SPIKE (Ours)	WSM	AdaPose	HRNet+RefiNet
	2018	2019	2020	2020	2021	-	2020	2021	2023
Modality	voxels	depth	points	points	depth	points	depth+points		
Head	98.29	98.54	-	96.73	93.87	98.42	98.15	98.42	-
Neck	99.07	99.20	-	98.05	97.90	99.47	99.47	98.67	-
Shoulders	97.18	96.23	-	94.38	95.22	97.48	94.69	95.39	-
Elbows	80.42	78.92	-	73.67	84.53	81.64	82.80	90.74	-
Hands	67.26	68.35	-	54.95	56.49	71.71	69.10	82.15	-
Torso	98.73	98.52	-	98.35	99.04	99.24	99.67	99.71	-
Hips	93.23	90.85	-	91.77	97.42	93.68	95.71	96.43	-
Knee	91.80	90.75	-	90.74	94.56	91.56	91.00	94.41	-
Feet	87.60	86.91	-	86.30	92.04	84.30	89.96	92.84	-
Upper B.	-	-	-	80.10	83.03	88.75	-	-	80.8
Lower B.	-	-	-	89.60	95.30	89.85	-	-	88.1
Mean	88.74	88.00	75.64*	85.11	88.75	<b>89.19</b>	89.59	<b>93.38</b>	84.2





1. **Sequence information is useful**, but up to a certain sequence length
2. Spatial Convolutions help to preserve spatial structure (useful for HPE)
3. **SOTA in ITOP**

- Future work:  
How does SPIKE perform with **real-world data**?





RQ1. Different inputs for behaviour measurement

RQ2. Robust performance for real-world HAR



Benchmarks

VS



Real-world data

*2.5D  
(self)-occlusions  
complex, natural activities  
unbalanced classes  
frontal vs. tilted angles  
sparsity and noise*

# Bathroom Activities Dataset (BAD)

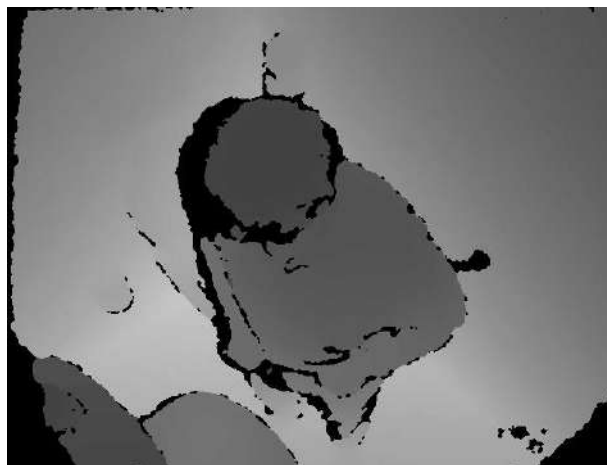
## Description

- 50 full sequences
- **19 subjects with dementia** using the toilet
- 8 classes: walking around, undressing, sitting down, sitting on the toilet, standing up, dressing, washing hands
- 2 different locations:
  - **BAD1**: 3 subjects (36k frames)
  - **BAD2**: 16 subjects (21k frames)
- **Unbalanced** dataset:  
E.g.: in BAD2: sitting: 8k frames vs. sitting down: 679 frames

BAD1 – 3 subjects



BAD2 – 16 subjects



# Domain Gaps

Performance gap between benchmarks and real-world datasets

Performance gap between real-world scenes

Human Activity Recognition				
P4T [2]	Tested on (acc.)			
Trained on	<i>MSRAAction3D</i>	<i>NTU 60 (cs)</i>	<i>BAD1 (cs)</i>	<i>BAD2 (cs)</i>
<i>MSRAAction3D</i>	90.94	-	-	-
<i>NTU 60 (cs)</i>	-	90.2	-	-
<i>BAD1 (cs)</i>	-	-	53.15	7.23
<i>BAD2 (cs)</i>	-	-	7.90	63.63
Human Pose Estimation				
SPiKE	Tested on (mAP@0.1m)			
Trained on	<i>ITOP-SIDE</i>		<i>ITOP-TOP</i>	
<i>ITOP-SIDE</i>	89.19		24.75*	
<i>ITOP-TOP</i>	36.81*		81.58*	

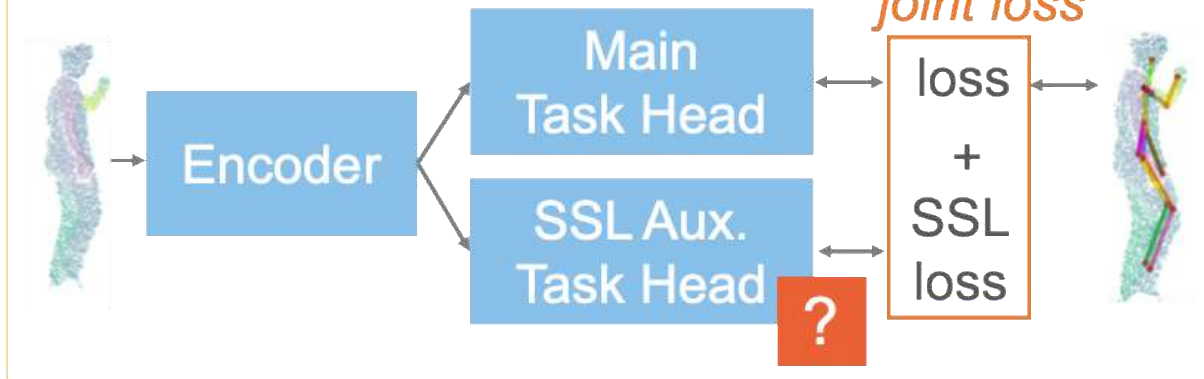
Performance gap between views

\*Work-in-progress

[2] Fan, H., Yang, Y., & Kankanhalli, M. (2021). Point 4d transformer networks for spatio-temporal modeling in point cloud videos. CVPR 2021

# Test-Time Training for Domain Adaptation in Point Cloud Sequences

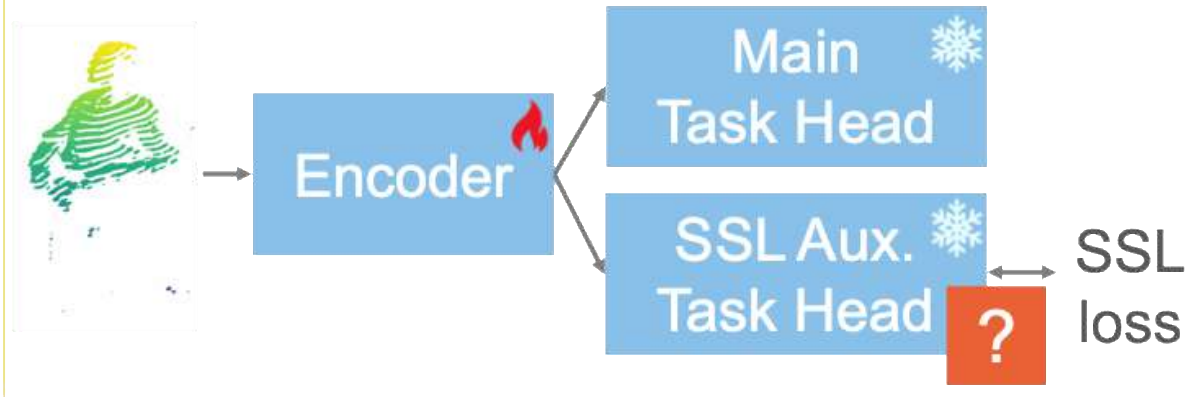
## Joint Training



*Source domain*

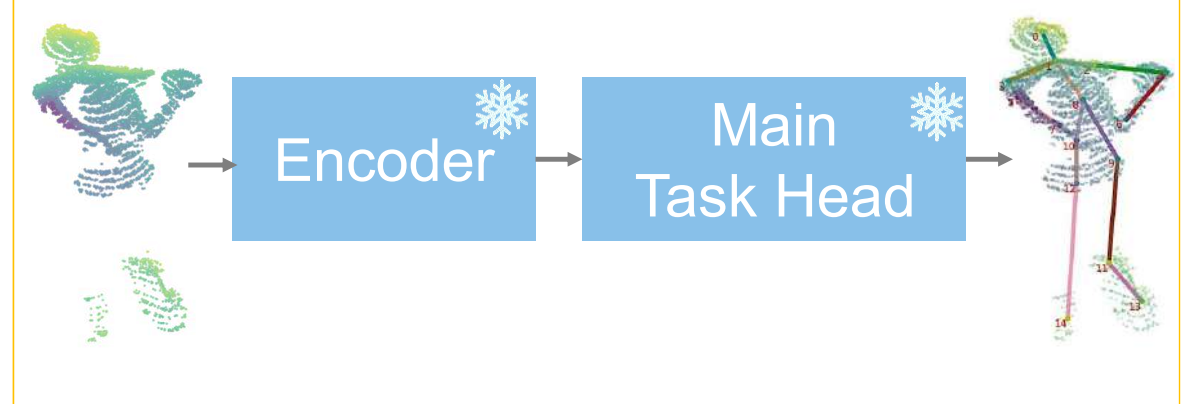
*Target domain*

## Test-Time Training



*Target domain*

## Inference



- **Take away message**

- Very promising achievements in benchmarks, how do they behave with real-world data?
- **Need for evaluation in real-world scenarios and (potentially) domain adaptation for AAL applications**

- Future work:

- Pre-training strategies
- Self-supervised learning
- Continual learning



# Thank you!

**Irene Ballester Campos**

**TU Wien**

irene.ballester@tuwien.ac.at

# *Measuring dementia behaviours through depth sensors*

Irene Ballester Campos  
irene.ballester@tuwien.ac.at



Innovative Training Network on  
Privacy-Aware and Acceptable Video-  
Based Technologies and Services for  
Active and Assisted Living



@visuAAL\_ITN



<https://www.visuaal-itn.eu/>



This project has received funding from the European Union's Horizon 2020 research and Innovation programme under the Marie Skłodowska-Curie grant agreement No 861091 and from the WWTF under the project number ICT20-055.